

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	1	10/772278	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/15 14:36
S2	343	(teach or communicate or impart or instruct or show) and (travel or path or trail or track or route) and (robot or automaton)and (time near3 series) and (accumulate or record or accrue or acquire) and (detect or find or observe or recognize) and (position) and (Move or advance or velocity or speed) and (distance)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/15 15:56
S3	453	"20030144765" "20040158358" "20040193321" "20040199288" "20050107918" "20050149231" "20050251290" "20050256611" "20060184275" "4385358" "4420812" "4442521" "4468695" "4491266" "4557386" "4613803" "4633059" "4761596" "4764883" "4772776" "4803640" "4836742" "4841113" "4879664" "4882527" "4919967" "4954762" "4967127" "5204598" "5228190" "5274360" "5327057" "5371836" "5463297" "5532924" "5590244" "5668628" "5715375" "5727132" "5760560" "5761390" "5783834" "5796610" "5920735" "6097169" "6133545" "6140788" "6321139" "6452134" "7149602"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 06:41
S4	343	(teach or communicate or impart or instruct or show) and (travel or path or trail or track or route) and (robot or automaton)and (time near3 series) and (accumulate or record or accrue or acquire) and (detect or find or observe or recognize) and (position) and (Move or advance or velocity or speed) and (distance)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 06:43

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S5	1	S3 and S4	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 06:43
S6	21	("20020007230" "5369346" "5402050" "5416393" "5594644" "5737217" "5823845" "5872893" "5982389" "6021363").PN. OR ("6493606"). URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/20 07:18
S7	11	("5432417" "5594644" "5838130" "5841258" "5872893" "6243623" "6289265" "6458011" "6463356" "6493606" "6580969").PN. OR ("7024276"). URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/20 08:47
S8	343	(teach or communicate or impart or instruct or show) and (travel or path or trail or track or route) and (robot or automaton)and (time near3 series) and (accumulate or record or accrue or acquire) and (detect or find or observe or recognize) and (position) and (Move or advance or velocity or speed) and (distance)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 11:18
S9	274	S8 and path	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 11:22
S10	268	S8 and path and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 11:22
S11	0	("2004/0158358").URPN.	USPAT	OR	ON	2007/02/20 11:24
S12	75	robot and autonomous and path and learn and teach and correct and time and series	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 14:27

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S13	1	6842692b2	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 14:27
S14	71	"4675502"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 16:14
S15	2	"20040158358"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 14:49
S16	33577	(taught or teach or learn) and path and correct	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 16:14
S17	1871	(taught or teach or learn) and path and (correct or fix) and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 16:15
S18	407	(taught or teach or learn) and path and (correct or fix) and robot and autonomous	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 16:54
S19	19	"836059"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/20 16:54

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S20	24	("4613942" "4675502" "4731860" "4803735" "4985846" "5066902" "5115403" "5255199" "5300868" "5319443" "5327058" "5380978" "5408409" "5440650" "5452370" "5481298" "5572102" "5572103" "5577130" "5579444" "5959425" "5987591").PN. OR ("6414711").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/20 16:56
S21	714	robot and (path or route or track or trail) and (autonomous) and (taught or learn or teach or train) and (correct or improve or rectify or review or revise)	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 08:11
S22	30	("3699316" "3789351" "4133404" "4470119" "4677562" "4688176" "4694639" "4772832" "4890233" "4919224" "5007234" "5155684" "5163273" "5272639" "5444965" "5777785" "5838562" "5925080" "5974347" "5986583" "6006161" "6012002" "6212476" "6240368").PN. OR ("6454036").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/21 08:01
S23	0	S21 and "teaching object"	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/21 08:01
S24	221	"teaching object"	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/21 08:01
S25	482	robot and (path or route or track or trail) and (autonomous) and (taught or learn or teach or train) and (correct or improve or rectify or review or revise) and time and (serial or series) and object	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 08:12
S26	396	robot and (path or route or track or trail) and (autonomous) and (taught or learn or teach or train) and (correct or improve or rectify or review or revise) and time and (serial or series) and object and distance and direction	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 08:14

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S27	3	robot and (path or route or track or trail) and (autonomous) and (taught or learn or teach or train) and (correct or improve or rectify or review or revise) and time and (serial or series) and object and distance and direction and "taught path"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 08:21
S28	1	robot and (path or route or track or trail) and (autonomous) and (taught or learn or teach or train) and (correct or improve or rectify or review or revise) and time and (serial or series) and object and distance and direction and follow near human	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 08:25
S29	321	taught same path same robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 08:25
S30	88	("4028533" "4119900" "4500970").PN. OR ("4638445").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/21 08:37
S31	2	person-following	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/21 08:37
S33	30	follow near person and robot	US-PGPUB; USPAT; USOCR	OR	ON	2007/02/21 08:38
S34	1	7024276b2	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 09:49
S36	1798	(700/264,245).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/02/21 11:30

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S37	17	(autonomous or self-propelled) and robot and learn and travel and path and follow with (instructor or human or object) and teach	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 13:51
S38	1	teach same path same robot same follow same instructor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 13:51
S39	4	teach and path and robot and follow same instructor	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 13:57
S40	0	"A Robot Controller Using Learning by Imitation"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 14:00
S42	254	(700/253).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/02/21 14:37
S43	4364	((700/245,250,253,258,259,264) or (382/103,153) or (901/1)).CCLS.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2007/02/21 14:21
S44	1683	S43 and path	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 14:21

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S45	1162	S44 and robot	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 14:37
S46	748	S45 and follow	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/02/21 14:37